



Uncertainty Quantification for High Frequency Waves

Gabriela Malenová

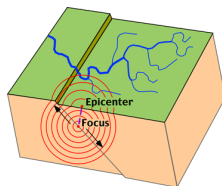
Royal Institute of Technology KTH

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Jointly with Olof Runborg, Mohammad Motamed, Raul Tempone

Problem statement

- Propagation of high-frequency waves with uncertain parameters.
- e.g. earthquakes: uncertain medium and source location



Simplified model: scalar wave equation with

1. Highly oscillatory initial data.
2. Uncertainty (initial data and/or model parameters).

Cauchy problem for the scalar wave equation

$$\begin{aligned}u_{tt}^\varepsilon(t, \mathbf{x}) &= c(\mathbf{x})^2 \Delta u^\varepsilon(t, \mathbf{x}), & (t, \mathbf{x}) \in \mathbb{R}^+ \times \mathbb{R}^n, \\u^\varepsilon(0, \mathbf{x}) &= A_0(\mathbf{x}) e^{i\Phi_0(\mathbf{x})/\varepsilon}, \\u_t^\varepsilon(0, \mathbf{x}) &= \frac{1}{\varepsilon} B_0(\mathbf{x}) e^{i\Phi_0(\mathbf{x})/\varepsilon}, & t = 0, \mathbf{x} \in \mathbb{R}^n,\end{aligned}$$

with c wave speed, Φ_0 initial phase, $\varepsilon \ll 1$ wavelength and A_0, B_0 amplitude parameters.

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Sources of uncertainty:

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\Rightarrow uncertainty in $u^\varepsilon = u^\varepsilon(t, \mathbf{x}, \mathbf{y})$.

Goals

- Consider quantity of interest

$$Q^\varepsilon(\mathbf{y}) = \int_{\mathbb{R}^n} |u^\varepsilon(T, \mathbf{x}, \mathbf{y})|^2 \psi(\mathbf{x}) d\mathbf{x}, \quad \psi \in C_c^\infty(\mathbb{R}^n).$$

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Proposed method:

1. Gaussian beam method.
2. Sparse stochastic collocation.

Layout

High frequency approximations

Geometrical optics

Gaussian beam method

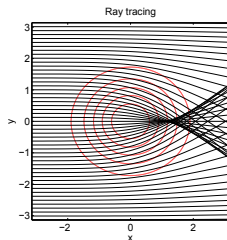
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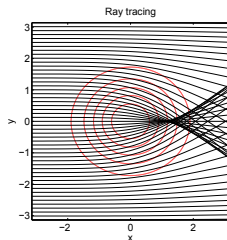
Numerical examples

Geometrical optics



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- Geometrical optics: approximation in the limit $\varepsilon \rightarrow 0$.
- GO breaks down at caustics.
- Remedy: Gaussian beam method.

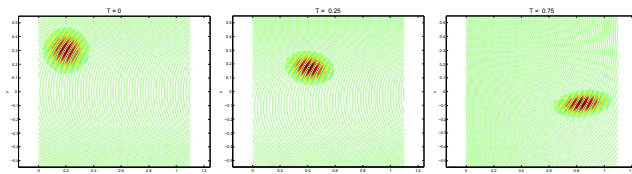
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Gaussian beams



- High-frequency approximation using same Ansatz as GO

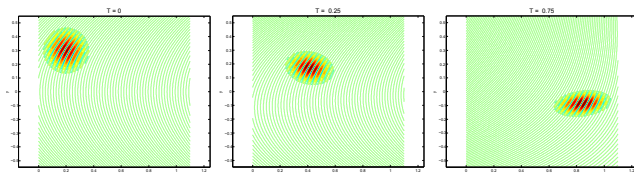
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with Φ and A Taylor expanded locally around GO ray $\mathbf{q}(t, \mathbf{y})$

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- Full solutions on a small $\sim \sqrt{\varepsilon}$ neighborhood around the ray.
- Φ has positive imaginary part away from the ray.

Gaussian beams

First order beams:

$$a(t, \mathbf{x}, \mathbf{y}) = a_0(t, \mathbf{y}), \quad \phi(t, \mathbf{x}, \mathbf{y}) = \phi_0(t, \mathbf{y}) + \mathbf{x} \cdot \mathbf{p}(t, \mathbf{y}) + \frac{1}{2} \mathbf{x} \cdot M(t, \mathbf{y}) \mathbf{x}.$$

- Require: $\Phi(t, \mathbf{x}, \mathbf{y})$ solves eikonal equation to $O(|\mathbf{x} - \mathbf{q}(t, \mathbf{y})|^3)$ and $A(t, \mathbf{x}, \mathbf{y})$ solves transport equation to $O(|\mathbf{x} - \mathbf{q}(t, \mathbf{y})|)$.

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- We obtain set of ODEs for $\mathbf{q}, \mathbf{p}, \phi_0, M, a_0$.



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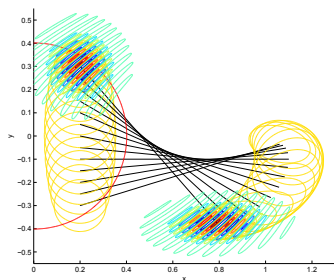
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- We obtain set of ODEs for $\mathbf{q}, \mathbf{p}, \phi_0, M, a_0$.
- Gaussian shape

$$\begin{aligned} |v^\varepsilon(t, \mathbf{x}, \mathbf{y})| &= a_0 \exp(-\text{Im}(\Phi)/\varepsilon) \\ &= a_0 \exp\left(-\frac{1}{2\varepsilon} (\mathbf{x} - \mathbf{q}(t, \mathbf{y})) \cdot \text{Im}(M) (\mathbf{x} - \mathbf{q}(t, \mathbf{y}))\right). \end{aligned}$$

- $M = M^T$ and $\text{Im}(M) > 0$ for all $t > 0$ if valid for initial data.

Gaussian beam superposition



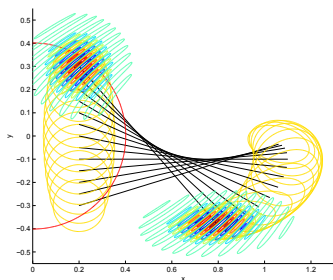
More general solutions \Rightarrow superpositions of Gaussian beams:

$$u_{GB}^\varepsilon(t, \mathbf{x}, \mathbf{y}) = \frac{1}{(2\pi\varepsilon)^{n/2}} \int_{K_0} v^\varepsilon(t, \mathbf{x}, \mathbf{y}; \mathbf{z}) d\mathbf{z},$$

$K_0 \subset \mathbb{R}^n$ compact, $\mathbf{z} \in K_0$ is starting point.



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- By wave equation linearity, sum of solutions is also a solution
- Accuracy $\|u(t, \cdot) - u_{GB}(t, \cdot)\|_E \leq C(t) \varepsilon^{1/2}$

Layout

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Gaussian beam method

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Numerical examples

Stochastic collocation

- Consider quantity of interest

$$Q^\varepsilon(\mathbf{y}) = \int_{\mathbb{R}^n} |u_{GB}^\varepsilon(T, \mathbf{x}, \mathbf{y})|^2 \psi(\mathbf{x}) d\mathbf{x}, \quad \psi \in C_c^\infty(\mathbb{R}^n).$$

where $\mathbf{y} \in \Gamma \subset \mathbb{R}^N$ (random).

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- Approximated by

$$\mathbb{E}[Q^\varepsilon(\mathbf{y})] \approx \sum_{k=1}^{\eta} \alpha_k Q^\varepsilon(\mathbf{y}^{(k)}),$$

where α weights associated to the points used.

- NOTE: one full solve of high-frequency problem needed for each \mathbf{y} value of $Q(\mathbf{y})$.

Sparse grid quadrature

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- Key point: choice of collocation point set $\{\mathbf{y}^{(k)}\}_{k=1}^{\eta} \in \Gamma$.

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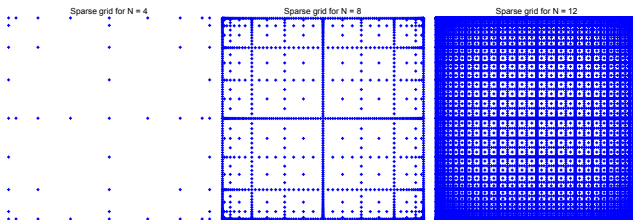
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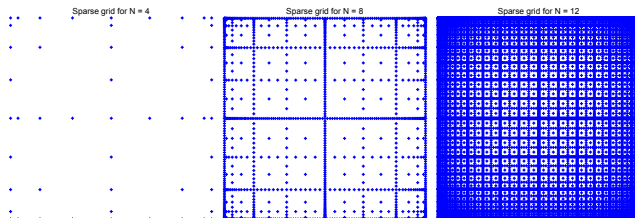
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- Standard quadrature slow when N large.
- Monte-Carlo better but limited to $\eta^{-1/2}$ rate.
- **Sparse grids** to reduce the cost.
- Sparse stochastic collocation faster if Q^ε smooth in \mathbf{y} .

Sparse grid quadrature



Smolyak sparse grid: nested points on Clenshaw-Curtis abscissas (extrema of Chebyshev polynomials) using total degree index set.

Sparse grid quadrature



Smolyak sparse grid: nested points on Clenshaw-Curtis abscissas (extrema of Chebyshev polynomials) using total degree index set.

- Number of collocation points grows slowly with N .
- Spectral convergence in η (number of collocation points)

$$\text{error} \leq C(p, N) M(Q^\varepsilon) \eta^{-\frac{p}{1+\log 2N}}, \quad \forall p.$$

- Rate depends on smoothness of Q^ε : size of $M \sim \left| \frac{d^\ell Q^\varepsilon}{dy^\ell} \right|$.
- Rate depends only weakly on N .

Stochastic regularity for high frequency waves

Stochastic Cauchy problem

$$u_{tt}^\varepsilon(t, \mathbf{x}, \mathbf{y}) = c(\mathbf{x}, \mathbf{y})^2 \Delta u^\varepsilon(t, \mathbf{x}, \mathbf{y}), \quad (t, \mathbf{x}, \mathbf{y}) \in \mathbb{R}^+ \times \mathbb{R}^n \times \Gamma,$$

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- Sources of uncertainty: speed, initial position, wave phase...
- For fast convergence we need

$$\sup_{\mathbf{y} \in \Gamma} \left| \frac{d^\ell Q^\varepsilon(\mathbf{y})}{d\mathbf{y}^\ell} \right| \leq C_\ell, \quad \forall \ell \in \mathbb{N}^N,$$

where C_ℓ independent of the wavelength ε .

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Stochastic regularity for high frequency waves

In general, $u^\varepsilon(t, \mathbf{x}, \mathbf{y})$ oscillates with period $\sim \varepsilon$ both in \mathbf{x} and \mathbf{y} .

Conjecture/Theorem

The bound

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with single family initial data.

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Numerical examples

Example 1: Caustics

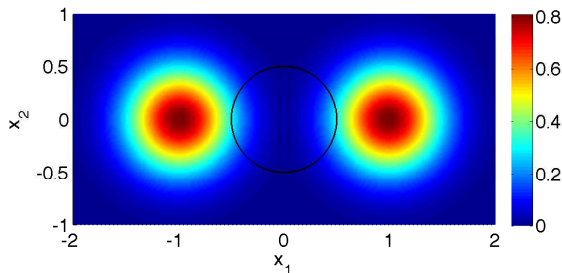


Figure: Two bumps moving towards each other (absolute value).

$$\Phi_0(\mathbf{x}) = |x_1| + x_2^2, \quad \mathbf{x} = (x_1, x_2).$$

Caustics appear for $t \geq 0.5$. Circle indicates the support of the QoI test function.

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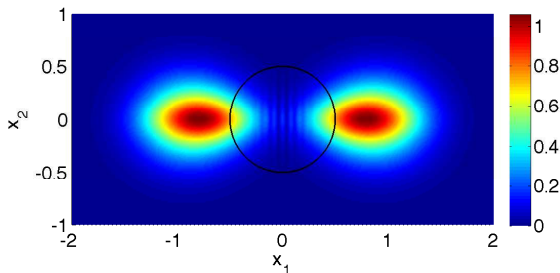


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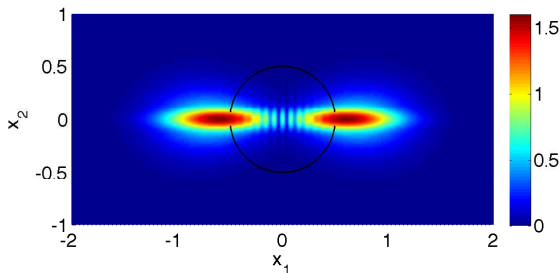


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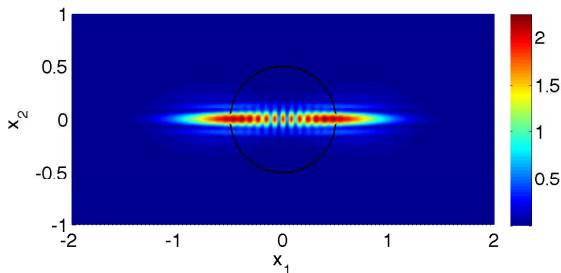


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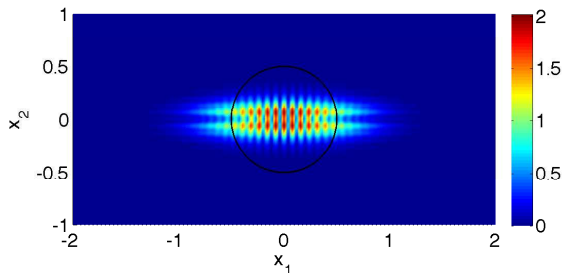


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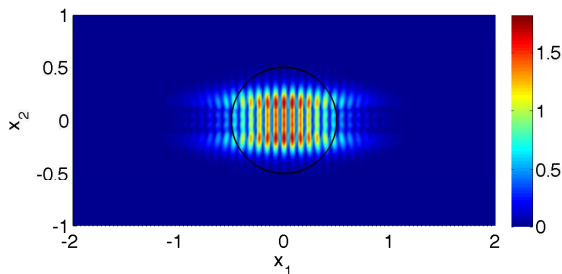


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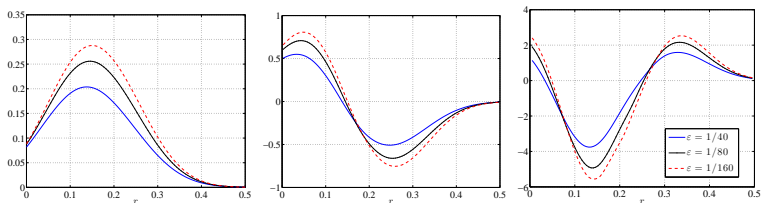
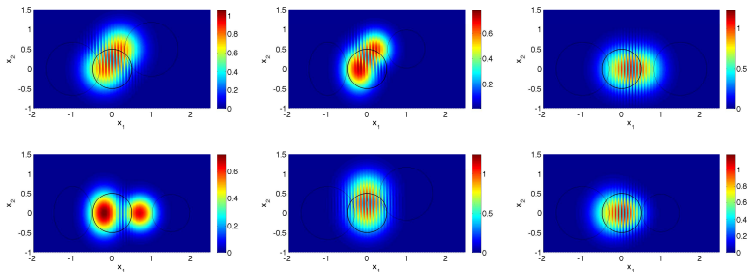


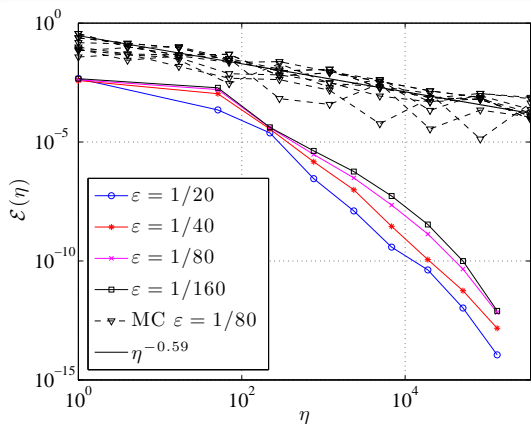
Figure : Quantity of interest $Q^\epsilon(\mathbf{y})$ with its first and second derivatives.

- $N = 2$ random variables – initial position (y_1) and constant speed (y_2).
- QoI along the line $\mathbf{y}(r) = (1 + r, 1 + 2r)$, for different wave lengths ϵ .

Example 2: Sparse grids

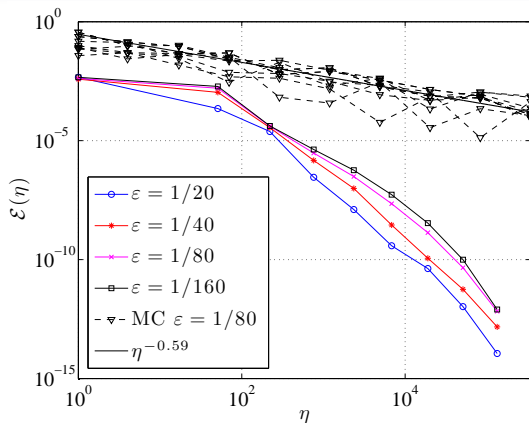


- $N = 5$ random variables (speed, initial data – pulse shape, position).
- $\Phi_0 = |x_1|$.



Relative error in the expected value of Q^ε for levels $\ell \geq 1$:

$$\mathcal{E}(\eta(\ell)) := \frac{\left| \mathbb{E}[\mathcal{S}_{I(\ell_{\text{ref}})}[Q^\varepsilon]] - \mathbb{E}[\mathcal{S}_{I(\ell)}[Q^\varepsilon]] \right|}{\left| \mathbb{E}[\mathcal{S}_{I(\ell_{\text{ref}})}[Q^\varepsilon]] \right|}.$$



- Fast spectral convergence compared to Monte-Carlo.
- As ε decreases, error converges \Rightarrow uniform bounds.

THANK YOU FOR YOUR ATTENTION